Machine Learning I

Bjoern Andres, Shengxian Zhao

Machine Learning for Computer Vision TU Dresden



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- This generalizes the problem of partitioning a set. It specializes to the latter for complete graphs.
- Analogously, the problem of decomposing a graph is introduced as an unsupervised learning problem w.r.t. constrained data.











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- ▶ A partition Π of the node set A is called a **decomposition (clustering)** of G iff, for every $U \in \Pi$, the subgraph $(U, E \cap {U \choose 2})$ of G induced by U is connected (and thus a component of G).

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- We denote by D_G the set of all decompositions of G.

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Lemma.

- ► For any decomposition of a graph *G*, the set of those edges that straddle distinct components is a multicut of *G*. This multicut is said to be **induced** by the decomposition.
- ► The map from decompositions to induced multicuts is a bijection from D_G to M_G.

Remarks:

The characteristic function y: E → {0,1} of a multicut y⁻¹(1) decides, for every edge {a,b} = e ∈ E, whether the incident nodes a and b belong to the same component (y_e = 0) or distinct components (y_e = 1).

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Lemma. For any $y: E \to \{0, 1\}$, the set $y^{-1}(1)$ of those edges that are mapped to 1 is a multicut of G iff the following inequalities are satisfied:

$$\forall C \in \mathsf{cycles}(G) \ \forall e \in C \colon \quad y_e \le \sum_{e' \in C \setminus \{e\}} y_{e'} \tag{1}$$

Constrained Data

We reduce the problem of learning and inferring multicuts to the problem of learning and inferring decisions, by defining **constrained data** (S, X, x, Y) with

$$S = E$$

$$\mathcal{Y} = \left\{ y : E \to \{0, 1\} \mid \forall C \in \mathsf{cycles}(G) \; \forall e \in C \colon y_e \leq \sum_{e' \in C \setminus \{e\}} y_{e'} \right\}$$
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- We consider linear functions. Specifically, we consider $\Theta = \mathbb{R}^V$ and $f: \Theta \to \mathbb{R}^X$ such that

$$\forall \theta \in \Theta \ \forall \hat{x} \in \mathbb{R}^{V} \colon \quad f_{\theta}(\hat{x}) = \sum_{v \in V} \theta_{v} \ \hat{x}_{v} = \langle \theta, \hat{x} \rangle \quad . \tag{4}$$



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- For any $v \in V$, let Θ_v be a random variable whose value is a real number $\theta_v \in \mathbb{R}$, a **parameter** of the function we seek to learn.
- Let Z be a random variable whose value is a subset $\mathcal{Z} \subseteq \{0,1\}^S$ called the set of **feasible decisions**. For clustering, we are interested in $\mathcal{Z} = \mathcal{Y}$, the set characterizing multicuts of G.



Factorization

 $P(X, Y, Z, \Theta) = P(Z \mid Y) \prod_{s \in S} P(Y_s \mid X_s, \Theta) \prod_{v \in V} P(\Theta_v) \prod_{s \in S} P(X_s)$

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$$P(\Theta \mid X, Y, Z) = \frac{P(X, Y, Z, \Theta)}{P(X, Y, Z)}$$

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 $\propto P(Y \mid X, \Theta) P(\Theta)$
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$$\propto P(Z \mid Y) P(Y \mid X, \Theta)$$
$$= P(Z \mid Y) \prod_{s \in S} P(Y_s \mid X_s, \Theta)$$

Distributions

► Logistic distribution

$$\forall s \in S: \qquad p_{Y_s|X_s,\Theta}(1) = \frac{1}{1 + 2^{-f_{\theta}(x_s)}}$$
 (5)



Distributions

• Normal distribution with $\sigma \in \mathbb{R}^+$:

$$\forall v \in V: \qquad p_{\Theta_v}(\theta_v) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\theta_v^2/2\sigma^2} \tag{6}$$



Distributions

Uniform distribution on a subset

$$\forall \mathcal{Z} \subseteq \{0,1\}^S \ \forall y \in \{0,1\}^S \quad p_{Z|Y}(\mathcal{Z},y) \propto \begin{cases} 1 & \text{if } y \in \mathcal{Z} \\ 0 & \text{otherwise} \end{cases}$$

Note that $p_{Z|Y}(\mathcal{Y},y)$ is non-zero iff the labeling $y\colon S\to\{0,1\}$ defines an multicut of G.

Lemma. Estimating maximally probable parameters $\theta,$ given attributes x and decisions y, i.e.,

$$\underset{\theta \in \mathbb{R}^{V}}{\operatorname{argmax}} \quad p_{\Theta | X, Y, Z}(\theta, x, y, \mathcal{Y})$$

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Proof. Analogous to the case of deciding, we obtain:

$$\underset{\theta \in \mathbb{R}^{V}}{\operatorname{argmax}} \quad p_{\Theta|X,Y,Z}(\theta, x, y, \mathcal{Y})$$

$$= \underset{\theta \in \mathbb{R}^{V}}{\operatorname{argmin}} \quad \sum_{s \in S} \left(-y_{s} f_{\theta}(x_{s}) + \log \left(1 + 2^{f_{\theta}(x_{s})} \right) \right) + \frac{\log e}{2\sigma^{2}} \|\theta\|_{2}^{2} .$$

Lemma. Estimating maximally probable decisions y, given attributes x, given the set of feasible decisions \mathcal{Y} , and given parameters θ , i.e.,

$$\underset{y \in \{0,1\}^S}{\operatorname{argmax}} \quad p_{Y|X,Z,\Theta}(y,x,\mathcal{Y},\theta) \tag{7}$$

assumes the form of the minimum cost multicut problem:

$$\underset{y: E \to \{0,1\}}{\operatorname{argmin}} \quad \sum_{e \in E} (-\langle \theta, x_e \rangle) y_e$$

$$\text{subject to} \quad \forall C \in \operatorname{cycles}(G) \ \forall e \in C \colon y_e \leq \sum_{e' \in C \setminus \{e\}} y_{e'}$$

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Theorem. The minimum cost multicut problem is NP-hard.

Bansal et al. (2004) reduce this problem to the k terminal cut problem whose NP-hardness is an important result Dahlhaus et al. (1994).

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For simplicity, we define $c:E\to \mathbb{R}$ such that

$$\forall e \in S: \quad c_e = -\langle \theta, x_e \rangle \tag{10}$$

and write the (linear) cost function $\varphi:\{0,1\}^E \to \mathbb{R}$ such that

$$\forall y \in \{0,1\}^E: \quad \varphi(y) = \sum_{e \in E} c_e \, y_e \tag{11}$$

Greedy joining algorithm:

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- It searches for decompositions with lower cost by joining pairs of neighboring (!) components recursively.
- ► As components can only grow and the number of components decreases by one in every step, one typically starts from the finest decomposition Π₀ of A into one-elementary components.

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- ▶ For any disjoint sets $B, C \subseteq A$, the pair $\{B, C\}$ is called **neighboring** in G iff there exist nodes $b \in B$ and $c \in C$ such that $\{b, c\} \in E$.
- For any decomposition Π of a graph G = (A, E), we define

$$\mathcal{E}_{\Pi} = \left\{ \{B, C\} \in {\Pi \choose 2} \mid \exists b \in B \, \exists c \in C \colon \{b, c\} \in E \right\} \quad .$$
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For any decomposition Π of G = (A, E) and any {B, C} ∈ E_Π, let join_{BC}[Π] be the decomposition of G obtained by joining the sets B and C in Π, i.e.

$$\mathsf{join}_{BC}[\Pi] = (\Pi \setminus \{B, C\}) \cup \{B \cup C\} \quad . \tag{13}$$

$$\begin{split} \Pi' &= \mathsf{greedy-joining}(\Pi) \\ & \mathsf{choose}\;\{B,C\} \in \operatornamewithlimits{argmin}_{\{B',C'\} \in \mathcal{E}_{\Pi}} \varphi(y^{\mathsf{join}_{B'C'}[\Pi]}) - \varphi(y^{\Pi}) \\ & \mathsf{if}\; \varphi(y^{\mathsf{join}_{BC}[\Pi]}) - \varphi(y^{\Pi}) < 0 \\ & \Pi' := \mathsf{greedy-joining}(\mathsf{join}_{BC}[\Pi]) \\ & \mathsf{else} \\ & \Pi' := \Pi \end{split}$$

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- The greedy moving algorithm is a local search algorithm that starts from any initial decomposition, e.g., the fixed point of greedy joining.
- It searches for decompositions with lower cost by recursively moving individual nodes from one component to a neighboring! component, possibly a new one.
- When a cut node is moved out of a component or a node is moved to a new component, the number of components increases. When the last element is moved out of a component, the number of components decreases.

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Lemma. For any graph G, the coarsest decomposition is unique. We denote it by Π_G^* .

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Lemma. For any graph G, the coarsest decomposition is unique. We denote it by Π_G^* .

Definition. For any graph G = (A, E), any decomposition Π of A and any $a \in A$, choose U_a to be the unique $U_a \in \Pi$ such that $a \in U_a$, and let

$$\mathcal{N}_{a} = \{\emptyset\} \cup \{W \in \Pi \mid a \notin W \land \exists w \in W \colon \{a, w\} \in E\}$$
(14)

$$G_a = \left(U_a \setminus \{a\}, E \cap \binom{U_a \setminus \{a\}}{2} \right)$$
(15)

For any $U\in\mathcal{N}_a,$ let ${\rm move}_{aU}[\Pi]$ the decomposition of A obtained by moving the node a to the set U, i.e.

$$\mathsf{move}_{aU}[\Pi] = \Pi \setminus \{U_a, U\} \cup \{U \cup \{a\}\} \cup \Pi^*_{G_a} \quad . \tag{16}$$

$$\begin{split} &\Pi' = \mathsf{greedy-moving}(\Pi) \\ &\mathsf{choose}\;(a,U) \in \operatornamewithlimits{argmin}_{a' \in A, \; U' \in \mathcal{N}_{a'}} \varphi(y^{\mathsf{move}_{a'U'}[\Pi]}) - \varphi(y^{\Pi}) \\ &\mathsf{if}\; \varphi(y^{\mathsf{move}_{aU}[\Pi]}) - \varphi(y^{\Pi}) < 0 \\ &\Pi' := \mathsf{greedy-moving}(\mathsf{move}_{aU}[\Pi]) \\ &\mathsf{else} \\ &\Pi' := \Pi \end{split}$$

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A generalization of this algorithm by means of the technique of Kernighan and Lin (1970) is analogous to the greedy moving algorithm for the set partition problem.

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- ► The supervised learning problem can assume the form of *l*₂-regularized logistic regression where samples are pairs of neighboring nodes and decisions indicate whether these nodes are in the same or distinct components
- The inference problem assumes the form of the NP-hard minimum cost multicut problem
- Local search algorithms for tackling this problem are greedy joining, greedy moving, and greedy moving using the technique of Kernighan and Lin.