

Intro to the OpenCV Library

for TU Dresden Computer Vision 2
lecture and general use

(some slides are cc from 'opencv 3.0' Kirill Korniyakov, Itseez)

Topics

1. Why
2. What
3. Install
4. Example Project
5. Your Task
6. Your Questions → in [Opal forum](#)

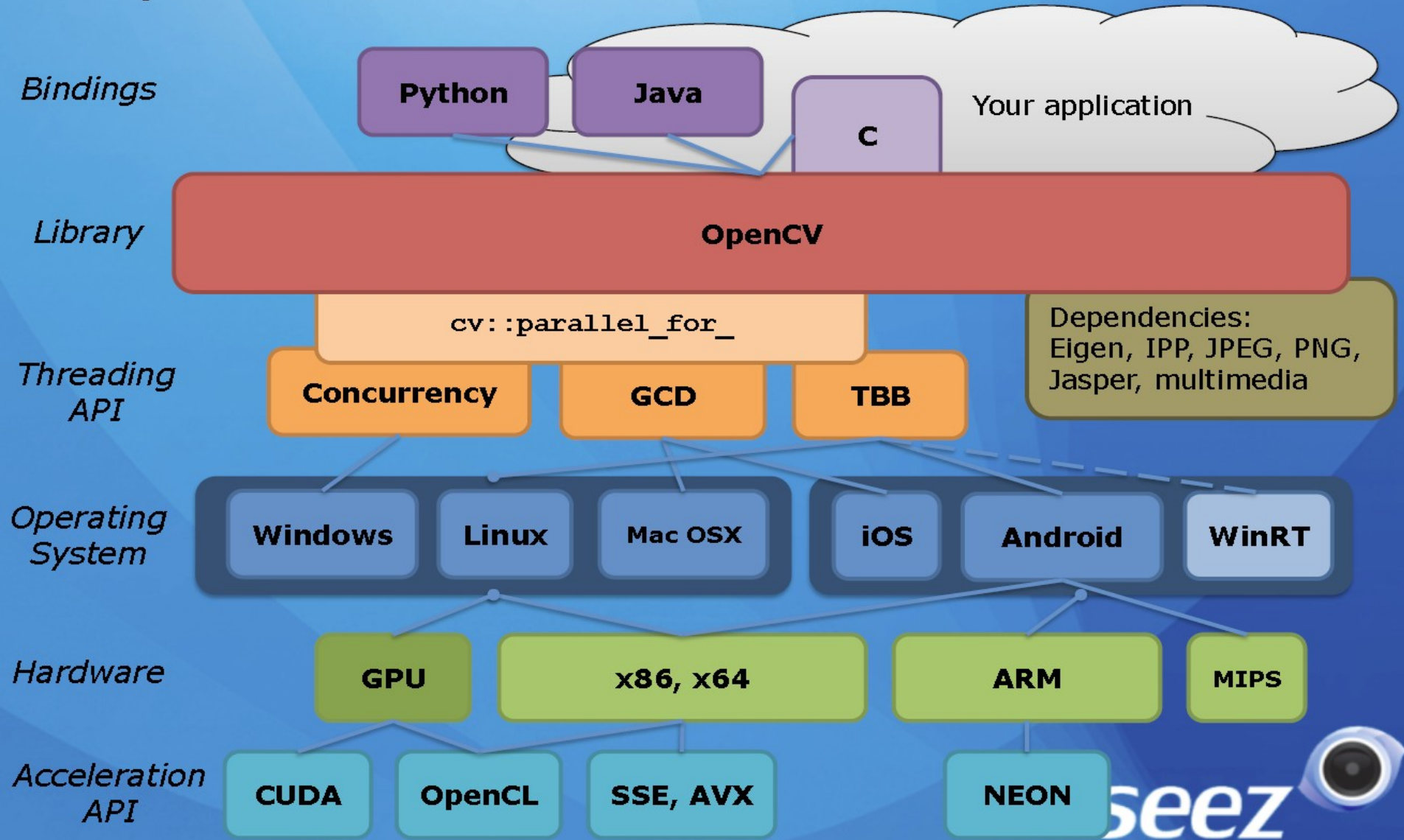
Why OpenCV?

1. 2,500+ algorithms and functions
2. Cross-platform, portable API
3. Real-time performance
4. Liberal BSD license
5. fast and regular updates

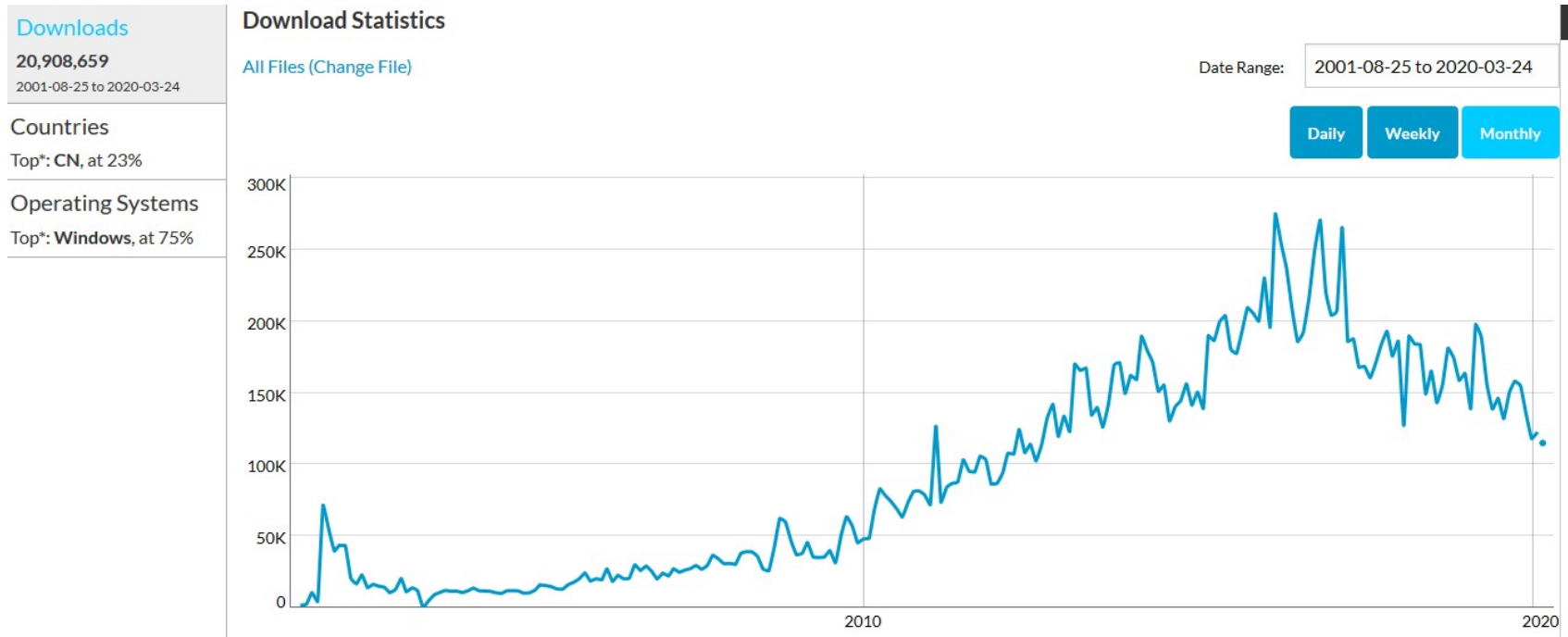


iOS

OpenCV Environment



History



2001: Intel → open src, 2008: Willow Garage, itSeez, 2010: Nvidia,
2016: Intel buys itSeez, Machine Learning rise (people move from cv to ml)

What? core module tutorials:



Mat - The Basic Image Container

How to scan images, lookup tables and time measurement with OpenCV

Mask operations on matrices

Adding (blending) two images using OpenCV

Changing the contrast and brightness of an image

Basic Drawing

Random generator and text with OpenCV

Discrete Fourier Transform

File Input and Output using XML and YAML files

What? imgproc module tutorials:

Smoothing Images

Eroding and Dilating

More Morphology Transformations

Image Pyramids

Basic Thresholding Operations

Making your own linear filters!

Adding borders to your images

Sobel Derivatives

Laplace Operator

Canny Edge Detector

Hough Line Transform

Hough Circle Transform

Remapping

Affine Transformations

Histogram Equalization

Histogram Calculation

Histogram Comparison

Back Projection

Template Matching

Finding contours in your image

Convex Hull

Creating Bounding boxes

and circles for contours

Creating Bounding rotated boxes

and ellipses for contours

Image Moments

Point Polygon Test

What?

Other modules:

Highgui:

Adding a Trackbar to our applications!

Video Input with OpenCV

Creating a video with OpenCV

calib3d:

Camera calibration

ml:

Support Vector Machines

Deep Neural Networks (dnn)

Principal Component Analysis

feature2d:

Harris corner detector

Shi-Tomasi corner detector

Creating your own corner

detector and

similarity measurement

Detecting corners location in

subpixels

Feature Description

Feature Matching with FLANN

Features2D + Homography to

find a known object

Detection of planar objects

objdetect:

Cascade Classifier

What? code examples:

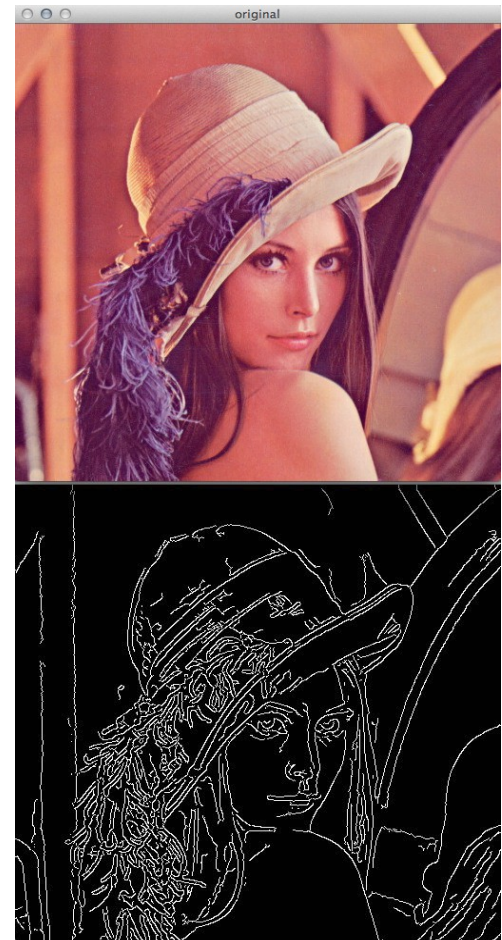
Hello World example shows an image:

```
int main(int argc, char** argv)
{
    Mat img = imread(argv[1], 1);
    imshow("", img);
    waitKey();
    return 0;
}
```

Hello
World!

What? code examples:

```
int main(int argc, char** argv)
{
    Mat img, gray;
    img = imread(argv[1], 1);
    imshow("original", img);
    cvtColor(img, gray, COLOR_BGR2GRAY);
    GaussianBlur(gray, gray, Size(7, 7),
                1.5);
    Canny(gray, gray, 0, 50);
    imshow("edges", gray);
    waitKey();
    return 0;
}
```



What? code examples:

Threshold:

```
Mat emptyPixImg = GrayImg < 1;
```

Image from (Camera- or) Directory-stream:

```
VideoCapture cap("TextureImages/Texture_%02d_inpaint.png");  
Mat Img;  
cap >> Img;
```

Create a 2D-Gaussian:

```
Mat Gauss2D = Mat::zeros(TemplateWidth, TemplateWidth,  
                          CV_32FC1);  
Gauss2D.at<float>( TemplateHW, TemplateHW) = 1.0;  
GaussianBlur(Gauss2D, Gauss2D, Size(TemplateWidth,  
                                     TemplateWidth), sigma, sigma);
```

What? code examples:

pointer work to speed up inner loops (useful in debug mode):

(1)

```
int** iim = new int*[h];
for (y=0; y<h; y++)
{
    iim[y] = IntegralImg.ptr<int>(y);
}
int diffy = 2*( iim[y][x+dx]      - iim[y][x-dx] ) +
              iim[y-dy][x-dx] - iim[y-dy][x+dx] +
              iim[y+dy][x-dx] - iim[y+dy][x+dx];
```

(2)

```
float *pCR, *pCRData = (float*) CorrResult.data;
*pCR = pCRData + y*w;
for ( int x = TemplateWidth; x < w-TemplateWidth; x++ )
{
    pCR[x] = ssd;    // write ssd result to result image
}
```

How?

1. Home: opencv.org
2. Documentation: docs.opencv.org
3. Q&A forum: answers.opencv.org
4. Report issues: github.com/opencv/opencv/issues
5. Develop: github.com/opencv/opencv

How? Install:

1. download:<https://github.com/opencv/opencv/>
 2. run Cmake(gui), check/install add-ons and configure until all problems have gone
create debug libs from source code, include Qt
generate makefile or .sln
 3. make / compile
 4. sudo make install (depending on environment)
(I use win+visual studio only currently, otherwise debian and kdevelop, QtCreator may also be a choice if you do not already have your environment)
 5. setup your IDE for OpenCV (set path, includes ...)
 6. run example(s)
- Thus you can run AND **debug into any OpenCV example** → good to read the code and for debugging

What YOU do:

1. download OpenCV source code from:
<https://github.com/opencv/opencv/>
2. Install additionally Libs (Qt, Eigen, ...) and compile OpenCV; create debug libs!
3. Setup IDE and run `edges` example

You have one week for this task.

What YOU do:

1. Set up your development environment and make a (simple ?) grey value transformation program.
2. You are free to use opencv and other example code you find,
3. but should
 - put it all together on your own
 - cite your source in a comment.
4. Good C++ [coding style](#) and a lot of comments!
5. Your code must compile without errors on Win and Linux systems (i.e. avoid Win-specific code).

Here is a link to the pdf for the [details of coding task](#).
You have another week for this coding task,
i.e. until 2020-04-20 (maybe more because of Easter).