# Machine Learning I

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#### Contents.

- This part of the course is about the problem of learning to order a finite set.
- ► This problem is introduced as an **unsupervised learning** problem w.r.t. **constrained data**.

We consider any finite, non-empty set A that we seek to order.

**Definition.** A strict order on A is a binary relation  $\leq \subseteq A \times A$  that satisfies the following conditions:

$$\forall a \in A \colon \neg a < a \tag{1}$$

$$\forall \{a, b\} \in \binom{A}{2}: \quad a < b \text{ xor } b < a$$
(2)

$$\forall \{a, b, c\} \in \binom{A}{3}: \quad a < b \land b < c \Rightarrow a < c \tag{3}$$

**Lemma.** The strict orders on A are characterized by the bijections  $\alpha: \{0, \ldots, |A| - 1\} \rightarrow A$ . For any such bijection, consider the order  $<_{\alpha}$  such that

$$\forall a, b \in A: \quad a < b \quad \Leftrightarrow \quad \alpha^{-1}(a) < \alpha^{-1}(b) \quad . \tag{4}$$

**Lemma.** The strict orders on A are characterized by those

$$y: \{(a,b) \in A \times A \mid a \neq b\} \to \{0,1\}$$
(5)

that satisfy the following conditions:

$$\forall a \in A \ \forall b \in A \setminus \{a\}: \quad y_{ab} + y_{ba} = 1 \tag{6}$$

$$\forall a \in A \ \forall b \in A \setminus \{a\} \ \forall c \in A \setminus \{a, b\} \colon \quad y_{ab} + y_{bc} - 1 \le y_{ac} \tag{7}$$

#### Constrained Data

We reduce the problem of learning and inferring orders to the problem of learning and inferring decisions, by defining constrained data (S,X,x,Y) with

$$S = \{(a,b) \in A \times A \mid a \neq b\}$$

$$\mathcal{Y} = \left\{ y \in \{0,1\}^S \mid \forall a \in A \forall b \in A \setminus \{a\} : \qquad y_{ab} + y_{ba} = 1 \\ \forall a \in A \forall b \in A \setminus \{a\} \forall c \in A \setminus \{a,b\} : \\ y_{ab} + y_{bc} - 1 \leq y_{ac} \right\}$$
(8)
$$(9)$$

#### Familiy of functions

- ▶ We consider a finite, non-empty set V, called a set of **attributes**, and the **attribute space**  $X = \mathbb{R}^V$
- We consider **linear functions**. Specifically, we consider  $\Theta = \mathbb{R}^V$  and  $f: \Theta \to \mathbb{R}^X$  such that

$$\forall \theta \in \Theta \ \forall \hat{x} \in \mathbb{R}^{V} \colon \quad f_{\theta}(\hat{x}) = \sum_{v \in V} \theta_{v} \ \hat{x}_{v} = \langle \theta, \hat{x} \rangle \quad .$$
 (10)





- For any (a, b) = s ∈ S = E, let X<sub>s</sub> be a random variable whose value is a vector x<sub>s</sub> ∈ ℝ<sup>V</sup>, the attribute vector of s.
- For any (a, b) = s ∈ S, let Y<sub>s</sub> be a random variable whose value is a binary number y<sub>s</sub> ∈ {0,1}, called the **decision** placing a before b.
- For any v ∈ V, let Θ<sub>v</sub> be a random variable whose value is a real number θ<sub>v</sub> ∈ ℝ, a parameter of the function we seek to learn.
- Let Z be a random variable whose value is a subset Z ⊆ {0,1}<sup>S</sup> called the set of **feasible decisions**. For ordering, we are interested in Z = Y, the set of characteristic functions of strict orders on A.



Factorization

 $P(X, Y, Z, \Theta) = P(Z \mid Y) \prod_{s \in S} P(Y_s \mid X_s, \Theta) \prod_{v \in V} P(\Theta_v) \prod_{s \in S} P(X_s)$ 

#### Factorization

► Supervised learning:

$$\begin{split} P(\Theta \mid X, Y, Z) &= \frac{P(X, Y, Z, \Theta)}{P(X, Y, Z)} \\ &= \frac{P(Z \mid Y) P(Y \mid X, \Theta) P(X) P(\Theta)}{P(Z \mid X, Y) P(X, Y)} \\ &= \frac{P(Z \mid Y) P(Y \mid X, \Theta) P(X) P(\Theta)}{P(Z \mid Y) P(X, Y)} \\ &= \frac{P(Y \mid X, \Theta) P(X) P(\Theta)}{P(X, Y)} \\ &\propto P(Y \mid X, \Theta) P(\Theta) \\ &= \prod_{s \in S} P(Y_s \mid X_s, \Theta) \prod_{v \in V} P(\Theta_v) \end{split}$$

#### Factorization

#### ► Inference:

$$P(Y \mid X, Z, \theta) = \frac{P(X, Y, Z, \Theta)}{P(X, Z, \Theta)}$$
$$= \frac{P(Z \mid Y) P(Y \mid X, \Theta) P(X) P(\Theta)}{P(X, Z, \Theta)}$$
$$\propto P(Z \mid Y) P(Y \mid X, \Theta)$$
$$= P(Z \mid Y) \prod_{s \in S} P(Y_s \mid X_s, \Theta)$$

#### Distributions

#### ► Logistic distribution

$$\forall s \in S: \qquad p_{Y_s|X_s,\Theta}(1) = \frac{1}{1 + 2^{-f_{\theta}(x_s)}}$$
(11)



#### Distributions

• Normal distribution with  $\sigma \in \mathbb{R}^+$ :

$$\forall v \in V: \qquad p_{\Theta_v}(\theta_v) = \frac{1}{\sigma\sqrt{2\pi}} e^{-\theta_v^2/2\sigma^2} \tag{12}$$



#### Distributions

#### Uniform distribution on a subset

$$\forall \mathcal{Z} \subseteq \{0,1\}^S \; \forall y \in \{0,1\}^S \quad p_{Z|Y}(\mathcal{Z},y) \propto \begin{cases} 1 & \text{if } y \in \mathcal{Z} \\ 0 & \text{otherwise} \end{cases}$$

Note that  $p_{Z|Y}(\mathcal{Y},y)$  is non-zero iff the labeling  $y\colon S\to\{0,1\}$  defines an order on A.

**Lemma.** Estimating maximally probable parameters  $\theta$ , given attributes x and decisions y, i.e.,

$$\underset{\theta \in \mathbb{R}^{V}}{\operatorname{argmax}} \quad p_{\Theta | X, Y, Z}(\theta, x, y, \mathcal{Y})$$

is an  $l_2$ -regularized logistic regression problem.

Proof. Analogous to the case of deciding, we obtain:

$$\underset{\theta \in \mathbb{R}^{V}}{\operatorname{argmax}} \quad p_{\Theta|X,Y,Z}(\theta, x, y, \mathcal{Y})$$

$$= \underset{\theta \in \mathbb{R}^{V}}{\operatorname{argmin}} \quad \sum_{s \in S} \left( -y_{s} f_{\theta}(x_{s}) + \log \left( 1 + 2^{f_{\theta}(x_{s})} \right) \right) + \frac{\log e}{2\sigma^{2}} \|\theta\|_{2}^{2} .$$

**Lemma.** Estimating maximally probable decisions y, given attributes x, given the set of feasible decisions  $\mathcal{Y}$ , and given parameters  $\theta$ , i.e.,

$$\underset{y \in \{0,1\}^S}{\operatorname{argmax}} \quad p_{Y|X,Z,\Theta}(y,x,\mathcal{Y},\theta) \tag{13}$$

assumes the form of the linear ordering problem:

$$\begin{array}{ll} \operatorname{argmin}_{y:\ S \to \{0,1\}} & \sum_{s \in S} (-\langle \theta, x_s \rangle) \, y_s & (14) \\ \operatorname{subject to} & \forall a \in A \ \forall b \in A \setminus \{a\} \colon & y_{ab} + y_{ba} = 1 & (15) \\ & \forall a \in A \ \forall b \in A \setminus \{a\} \ \forall c \in A \setminus \{a,b\} \colon & \\ & y_{ab} + y_{bc} - 1 \leq y_{ac} & (16) \end{array}$$

Theorem. The linear ordering problem is NP-hard.

The linear ordering problem has been studied intensively. A comprehensive survey is by Martí and Reinelt (2011). Pioneering research is by Grötschel (1984).

We define two local search algorithms for the linear ordering problem.

For simplicity, we define  $c:S\to \mathbb{R}$  such that

$$\forall s \in S: \quad c_s = -\langle \theta, x_s \rangle \tag{17}$$

and write the (linear) cost function  $\varphi:\{0,1\}^S \to \mathbb{R}$  such that

$$\forall y \in \{0,1\}^S \colon \quad \varphi(y) = \sum_{s \in S} c_s y_s \tag{18}$$

#### Greedy transposition algorithm:

- ► The greedy transposition algorithm starts from any initial strict order.
- It searches for strict orders with lower objective value by swapping pairs of elements

**Definition.** For any bijection  $\alpha : \{0, \ldots, |A| - 1\} \to A$  and any  $j, k \in \{0, \ldots, |A| - 1\}$ , let  $\operatorname{transpose}_{jk}[\alpha]$  the bijection obtained from  $\alpha$  by swapping  $\alpha_j$  and  $\alpha_k$ , i.e.

$$\forall l \in \{0, \dots, |A| - 1\}: \quad \text{transpose}_{jk}[\alpha](l) = \begin{cases} \alpha_k & \text{if } l = j \\ \alpha_j & \text{if } l = k \\ \alpha_l & \text{otherwise} \end{cases}$$
(19)

$$\begin{split} \alpha' &= \mathsf{greedy-transposition}(\alpha) \\ \mathsf{choose}\ (j,k) \in \mathop{\mathrm{argmin}}_{0 \leq j' < k' < |A|} \varphi(y^{\mathrm{transpose}_{j'k'}[\alpha]}) - \varphi(y^{\alpha}) \\ \mathsf{if}\ \varphi(y^{\mathrm{transpose}_{jk}[\alpha]}) - \varphi(y^{\alpha}) < 0 \\ \alpha' &:= \mathsf{greedy-transposition}(\mathrm{transpose}_{jk}[\alpha]) \\ \mathsf{else} \\ \alpha' &:= \alpha \end{split}$$

# Greedy transposition using the technique of Kernighan and Lin (1970)

 $\alpha' =$ greedy-transposition-kl $(\alpha)$  $\alpha^0 := \alpha$  $\delta_0 := 0$  $J_0 := \{0, \dots, |A| - 1\}$ t := 0(build sequence of swaps) repeat choose  $(j,k) \in \operatorname{argmin} \varphi(y^{\operatorname{transpose}_{j'k'}[\alpha^t]}) - \varphi(y^{\alpha^t})$  $\{(i',k') \in J_{\pm}^2 | i' < k'\}$  $\alpha^{t+1} := \mathsf{transpose}_{ik}[\alpha_t]$  $\delta_{t+1} := \varphi(y^{\alpha^{t+1}}) - \varphi(y^{\alpha^{t}}) < 0$  $J_{t+1} := J_t \setminus \{j, k\}$ (move  $\alpha_i$  and  $\alpha_k$  only once) t := t + 1until  $|J_t| < 2$  $\hat{t} := \min \operatorname{argmin}_{t' \in \{0, \dots, |A|\}} \sum_{\tau=0}^{t'} \delta_{\tau}$ (choose sub-sequence) if  $\sum_{\tau=0}^{\cdot} \delta_{\tau} < 0$  $\alpha' :=$ greedy-transposition-kl $(\alpha^{\hat{t}})$ (recurse) else  $\alpha' := \alpha$ (terminate)

# Summary.

- ► Learning and inferring orders on a finite set A is an unsupervised learning problem w.r.t. constrained data whose feasible labelings characterize the strict orders on A.
- The supervised learning problem can assume the form of  $l_2$ -regularized logistic regression where samples are pairs  $(a, b) \in A^2$  such that  $a \neq b$  and decisions indicate whether a < b.
- ► The inference problem assumes the form of the NP-hard linear ordering problem
- Local search algorithms for tackling this problem are greedy transposition and greedy transposition using the technique of Kernighan and Lin.